Two manifestations of rigidity phenomena in random point sets : forbidden regions and maximal degeneracy

> Subhro Ghosh National University of Singapore

Subhro Ghosh National University of Singapore Rigidity Phenomena

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- Namely, given a domain *D*, how does the point configuration outside of *D* impact the distribution of the points inside *D* ?
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Instances of rigidity

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- So, this amounts to a local law of conservation of mass : we are not allowed to perturb the point configuration in ways that create new particles or delete existing ones !
- This has implications in the study of stochastic geometry on these point processes, notably in the use of Burton and Keane type arguments, or the "finite energy" property.

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- Rigidity of particle numbers was also established for the zeros of the planar Gaussian analytic function [G. Peres]

$$f(z) = \sum_{k=0}^{\infty} \xi_k \frac{z^k}{\sqrt{k!}}.$$

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- Projection kernel in the above is necessary ! [G.-Krishnapur]

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• Natural to ask about rigidity of more general functionals of a point process (other than the particle count), particularly higher moments of the points in *D*.

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- These are the only rigid observables !
- For the standard planar case ($\alpha = 1$), this implies that the total mass as well as the centre of mass of the points in a bounded domain are determined by the outside point configuration.
- In particular, if there happens to be only one point in a bounded domain (an event of positive probability), then the exact location of that point is completely determined by the outside configuration.

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• Rigidity is also connected with faster decay of hole probabilities and singularity of Palm measures

(Moment-matching) [G.] Consider a point process Π having precisely the first *m* moments rigid, and two collections of points <u>ζ</u> = (ζ₁, · · · , ζ_k) and <u>η</u> = (η₁, · · · , η_l). Then Palm measures [Π]_{<u>ζ</u>} and [Π]_{<u>η</u>} are mutually absolutely continuous iff the first *m* moments of <u>ζ</u> and <u>η</u> match,

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• However, very few rigorous theorems establishing general implications like the above between these concepts.

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- When radius(D) $\rightarrow \infty$, how does the outside configuration behave ?
- In other words, what causes a large hole (a rare event) to occur ?

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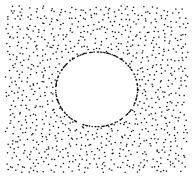
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- When radius(D) $\rightarrow \infty$, how does the outside configuration behave ?
- In other words, what causes a large hole (a rare event) to occur ?
- The most interesting scale to look at this question turns out to be the scale when the "hole" is rescaled to have size 1.

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Ginibre Ensemble

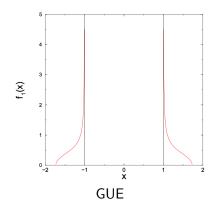
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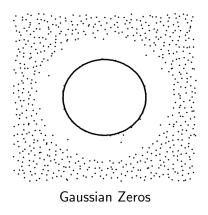
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The conditional intensity for zeroes of Gaussian random polynomials has the following behaviour:

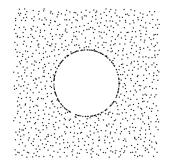
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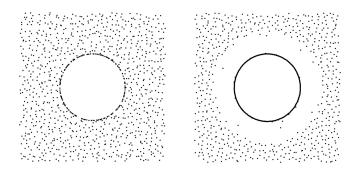
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- No zeros in the hole D is the same as $\underline{Z}(D) = 0$.
- To find the "most likely configuration" given that there is hole is roughly the same as minimizing the rate functional *I* over the space of probability measures (on \mathbb{C}) under the constraint that there is zero mass on *D*.

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- The functional to be optimized is highly non-smooth :

$$I(\mu) = 2 \sup_{z \in \mathbb{C}} \left\{ U_{\mu}(z) - \frac{|z|^2}{2} \right\} - \Sigma(\mu) - C,$$

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• Heuristics made rigorous by obtaining "effective" versions of large deviation estimates and approximating the analytic function zeros by those of the polynomials.

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- Nomenclature "stealthy" because such systems are invisible to diffraction experiments with waves having frequency inside the "gap".
- Stealthy particle systems conjectured to have deterministically bounded holes [Zhang-Stillinger-Torquato].

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Special case : Guassian process with a gap (or fast decay) in the spectrum

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- The existence of a gap / fast decay in the spectrum can be exploited to construct linear functionals of the process which have low variance.
- A linear functional with a low variance is approximately constant, so this gives an approximate linear constraint
- Sufficiently rich class of such constraints can be exploited to deduce degenerate behaviour.

Thank you !!

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